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FACSIMILE COVER SHEET

To: Commissioner for Patents for Examiner Ari M. Diacou Group Art Unit 3663	Facsimile No. 571/273-5591
From: Jeanine A. Graunke Legal Assistant to Neil G. Ferrari	No. of Pages Including Cover Sheet: 6

Enclosed herewith:

- Applicant Initiated Interview Request Form (PTOL-413A); and
- Agenda for Telephone Interview.

Re: Application Serial No. 10/696,788 Attorney Docket No. 16569-US

Date: March 18, 2009

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PTOL-413A (10-07) Approved for use through 10/31/2007, OMB 0651-0031 U.S. Patent and Trademark Office: U.S. DEPARTMENT OF COMMERCE

	Applicar	nt Initiated Inter	rview Request	Form			
Application No.: 10/ Examiner: Art M. placou	/696,788	First Named Applicant: Han et al. Art Unit: 3663 Status of Application: Office Action					
Tentative Participa	ints:						
		(4)					
Proposed Date of Interview: 3/23/09 or 3/24/09 Proposed Time: 2:00 p.m. ET (AM/P							
Type of Interview F (1) Telephonic	Requested: (2) ☐ Perso	onal (3) 🔲 Vi					
Exhibit To Be Show If yes, provide brief	/n or Demonstr: { description:	ated: TYES	□ NO		_		
Issues To Be Discussed							
Issues (Rej., Obj., etc)	Claims/ Fig. #s		Discussed	Agreed	Not Agreed		
(1) See Agenda	Maga nu	Prior Art					
(2)							
(3)							
(4) Continuation She	eet Attached						
Brief Description of	Arguments to l	e Presented:					
Please see attached A	Agenda						
NOTE: This form she (see MPEP § 713.01).	ould be completed	above-identified app d by applicant and sub	omitted to the examir				
This application will n interview. Therefore, as soon as possible.	of be delayed from applicant is advis	m issue because of app sed to file a statement o	dicant's failure to su of the substance of th	bmit a written a ais interview (37	fecord of this FCFR 1.133(b))		
Applicant/Applicar	nt's Representati il G. Ferrari	ve Signature	Examiner/SPE Signature				
Typed/Printed Name		Representative					
Registration	Number, if appli	icable					

This collection of information is required by 37 CFR 1.133. The information is required to obtain or retain a benefit by the public which is to file (and by the USPTO to process) an application. Confidentiality is governed by 35 U.S.C. 122 and 37 CFR 1.11 and 1.14. This collection is estimated to take 21 minutes to complete, including gathering, preparing, and submitting the completed application form to the USPTO. Time will vary depending upon the individual case. Any comments on the amount of time you require to complete this form and/or suggestions for reducing this burden, should be sent to the Chief Information Officer, U.S. Patent and Trademark Office, U.S. Department of Commerce, P.O. Box 1450, Alexandria, VA 22313-1450. DO NOT SEND FEES OR COMPLETED FORMS TO THIS ADDRESS. SEND TO: Commissioner for Patents, P.O. Box 1450, Alexandria, VA 22313-1450.

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

888888

In re application of: Han et al.

Serial No.: 10/696,788

Filed: October 30, 2003

For: Vehicular Guidance System Having Compensation for Variations in Ground

Elevation

Group Art Unit: 3663

Examiner: Diacou, Ari M.

Confirmation No.: 8112

Attorney Docket No.: 16569-US

78833
PATENT TRADEMARK OFFICE CUSTOMER NUMBER

Commissioner for Patents P.O. Box 1450 Alexandria VA 22313-1450

AGENDA FOR TELEPHONE INTERVIEW

Sir:

I would like to request a telephone interview on Monday or Tuesday, March 23, 2008 or March 24, 2008, at 2:00 Eastern time, or any time in the near future that is mutually convenient. Please consider the following topics for discussion.

Applicants request a copy of the Stewart reference.

Proposed Arguments:

The proposed combination of references, considered as a whole, fails to teach or suggest the feature of, "wherein each of the roll data and pitch data are separately estimated using i) a maximum slope of ground with respect to a reference point for each cell traversed by the vehicle corresponding to the particular location...and ii) an aspect angle between a direction of the maximum slope and an axis with which a direction of travel is coincident."

This cited portion of *Quincke* teaches calculating a location. Specifically, *Quincke* teaches calculating a location when traveling in the N-S direction on a slope inclined transversely

to the longitudinal direction of the equipment. However, from this equation, Quincke does not teach or suggest a maximum slope of the ground with respect to a reference point for each cell traversed by the vehicle corresponding to a particular location. Quincke is completely devoid of teaching a maximum slope of the ground. Futhermore, Quincke does not teach or suggest a maximum slope with respect to a reference point for each cell. The above matrix equation gives no indication as to what the symbols represent. Additionally, the matrix equations above result in three number, Xp, Yp, and Zp. Since the matrix equation results in a point on a map (X, Y, Z), this would not even allow an estimation of pitch and roll data as in claim 21. The Examiner equates β with roll data and X, Y, and Z with the reference point in claim 21. Even assuming, in arguendo, that the assumptions by the Examiner are true, Quincke would teach using the roll data to determine a reference point. Quincke would still not teach using the maximum slope, which is not taught in Quincke at all, for each cell to estimate the roll and pitch data.

Figure 7 of Quincke gives meaning to the symbols used in the matrix equation above. The symbol β describes the angle between the x axis and the slope of the ground where the vehicle in Quincke is located. Quincke teach away from using a maximum slope of the ground with respect to a reference point for each cell traversed by the vehicle corresponding to a particular location in estimating roll and pitch data. In Quincke, the symbol β is the roll angle of the vehicle in Figure 7 and not the angle of the maximum slope used to estimate roll and pitch data in claim 21.

The Examiner further states that Quincke "discloses alignment angle Φ which is in the N-S-E-W plane, and therefore the aspect angle Φ will be between the two directions claimed," to teach or suggest an aspect angle between a direction of the maximum slope and an axis with which a direction of travel is coincident is used in estimating pitch and roll data, as in claim 21. The angle Φ is the angle between d1 and the N-S direction. D1 is the projection of the distance from the location of the GPS antenna to the reference point. Therefore, the angle Φ in Quincke is the angle between the direction of the reference point and the N-S direction. Figure 2 of Quincke shows the angle Φ . The angle Φ in Quincke is not the same as the aspect angle in claim 21. The aspect angle in claim 21 is the angle between a direction of the $\frac{1}{1}$ maximum slope and an axis with which a $\frac{1}{1}$ direction of travel is coincident. Even if, in $\frac{1}{1}$ arguendo, the axis with which a direction of travel is coincident is the same as the N-S direction, $\frac{1}{1}$ $\frac{$

Page 2 of 4 Han et al. - 10/696,788 maximum slope. Furthermore, Quincke does not teach or suggest using this angel to estimate pitch and roll data.

The proposed combination of references, considered as a whole, fails to teach or suggest the feature of, "guiding the vehicle steering in a direction of travel with compensation data based upon at least one of the estimated roll data and the pitch data such that an actual path of the vehicle follows a target path."

The cited portion of Quincke teaches that a when a processing unit finds a virtual reference point, it takes into consideration a parameter of the equipment, such as speed, so that the position of the virtual reference point relative to a satellite reception unit (GPS antenna) can be regulated dynamically as a function of the parameter. When the reference point has reached the end of the field, certain operations are triggered automatically with an adjustable time lag. The certain operations could be lifting a cutterbar or lifting and turning the plow. Alternatively, in Quincke the parameter may be a cultivation tool mounted on the equipment to form the virtual reference point. The virtual reference point may be in each case located at the edge of a spreading range. However, the cited portion of Quincke is completely devoid of guiding the vehicle steering in a direction of travel with compensation data based upon at least one of the estimated roll data and the pitch data such that an actual path of the vehicle follows a target path. The cited portion of Quincke has nothing to do with the steering of a vehicle. In contrast, the cited portion of Quincke is directed towards a virtual reference point which is used in conjunction with a satellite to determine when operations need to be triggered. At best, Quincke is guiding the vehicle when Quincke determines that the plow needs to be turned, but this is not based on roll or pitch data. Additionally, Quincke does not teach or suggest a target path, but merely determines when an operation needs to be triggered.

The Examiner is invited to call at the below-listed telephone number to confirm or reschedule the requested telephone interview.

DATE: March 18, 2008

Respectfully submitted,

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